Search Algorithms

Generic Search Covered in Class

1: procedure Search(G, S, goal)2: Inputs

- 3: G: graph with nodes N and arcs A 4:
 - s: start node
 - goal: Boolean function of nodes

6: Output 7:

5:

8:

- path from s to a node for which goal is true
- or \perp if there are no solution paths

9: Local

- 10: Frontier: set of paths
- Frontier := $\{\langle s \rangle\}$ 11:
- while Frontier \neq {} do 12:
- select and remove $\langle n_0, \ldots, n_k
 angle$ from Frontier 13:
- if $goal(n_k)$ then 14:
- return $\langle n_0, \ldots, n_k \rangle$ 15:
- $ext{Frontier} := ext{Frontier} \cup ig \langle n_0, \ldots, n_k, n
 angle : \langle n_k, n
 angle \in A ig \}$ 16:
- 17: return 🔟

DFS Version



Racket Code

| 3 | (define (DFS maze) |
|---|--|
| 4 | ;; define local variables |
| 5 | (let ([start-node (list null maze)] |
| 6 | [frontier (make-stack)] |
| 7 | [visited-states (make-set)] |
| 8 | [current-node null]) |
| 9 | ;; set the initial values for the current node and frontier |
| 0 | (set! current-node start-node) |
| 1 | (set! frontier (push-stack start-node frontier)) |
| 2 | ;; loop through frontier |
| 3 | (for ([i (in-naturals)] |
| 4 | ;; break if the frontier is empty or the goal is found |
| 5 | #:break (or |
| 6 | (empty? frontier) |
| 7 | (is-goal (second current-node)))) |
| 8 | ;; pop the next value off the frontier |
| 9 | (set!-values (current-node frontier) (pop-stack frontier)) |
| 0 | ;; add the visited state to the froniter |
| 1 | (set! visited-states |
| 2 | (push-set |
| 3 | ;; visited states should contain just the state, not the path to it |
| 4 | (second current-node) |
| 5 | visited-states)) |
| 6 | ;; Loop through all successors and add them to the frontier |
| / | (for (lsuce |
| ö | (get-succ |
| 9 | (second surveys are determined from the state, not the safe + path |
| 1 | (second current-node)) |
| 2 | tuning (incompared states to the front states)) |
| 2 | ", differs (Lismeniae); (Second Successor) |
| 4 | (set frontier |
| 5 | (bush-stack |
| 6 | :: build the next node to appear on the frontier, this must include the full path and the successors state |
| 7 | (list |
| 8 | ;; add the new action on to the front of the path-so-far (we will reverse this path at the end |
| 9 | (cons (first succ) (first current-node)) |
| 0 | (second succ)) |
| 1 | frontier))) |
| 2 |) |
| 3 | ;; if the goal was found return the path to it |
| 4 | (if (is-goal (second current-node)) |
| 5 | (reverse (first current-node)) |
| 6 | ;; other wise return false |
| 7 | #f))) |

Same Thing Without the Comments

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

Side-by-side



Some Things not Addressed in the Pseudo Code

- Loops and tracking visited states
 - The pseudo code does not try to avoid loops, but exploring loops can easily blow up your frontier
- Separate action and state representations
 - In the racket code the frontier must store a representation of the final state in addition to paths so successors can be generated
- What is pushed to the frontier must be a deep copy of the path so far
 - The problem of mutability doesn't come up much in functional languages like Racket, but this can cause a lot of bugs in languages with more mutability like C, Java and Python



Define Local Variables



Set Initial Values



Loop through the frontier

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited_states (make_set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

We need to test both break conditions here since unlike the break statement in the pseudocode, we don't have a mid-loop break statement

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

Pop the next value off the frontier



Push the expanded state onto the set of visited states



A state is not the same as a frontier node which is a path + a state, so we only add the state to the visited states



Loop through successors to add them to the frontier



Do not add previously visited states to the frontier

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

Astute students will notice that if a state got added to the frontier twice before it was expanded we aren't filtering it. This is not enough of a problem in pacman to blow up the frontier, but a better solution would solve it. Perhaps implement visited-states as a hash table



Push the successor's state plus it's full path onto the frontier

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

The full path is built by adding the action to get from the current state to the successor to the path to get to the current state

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

In Racket, as in many functional languages, adding an element to the front of a list may be easier than adding it to the back of a list

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

For this reason, this solution adds the actions in reversed order, and then reverses the path at the end.



Once the loop is broken, return the appropriate output.

59 (define (DFS maze) 60 (let ([start-node (list null maze)] 61 [frontier (make-stack)] 62 [visited-states (make-set)] 63 [current-node null]) 64 (set! current-node start-node) 65 (set! frontier (push-stack start-node frontier)) 66 (for ([i (in-naturals)] 67 #:break (or 68 (empty? frontier) 69 (is-goal (second current-node)))) 70 (set!-values (current-node frontier) (pop-stack frontier)) 71 (set! visited-states 72 (push-set 73 (second current-node) 74 visited_states)) 75 (for ([succ 76 (get-succ 77 (second current-node))] 78 #:unless (ismember? (second succ) visited-states)) 79 (set! frontier 80 (push-stack 81 (list 82 (cons (first succ) (first current-node)) 83 (second succ)) 84 frontier))) 85 86 (if (is-goal (second current-node)) 87 (reverse (first current-node)) 88 #f)))

No mazes without solutions were given as examples, so we will not test what you return if the search fails.

BFS Version

```
59
    (define (BFS maze)
60
      (let ([start-node (list null maze)]
61
             [frontier (make-queue)]
62
             [visited-states (make-set)]
63
             [current-node null])
64
        (set! current-node start-node)
65
        (set! frontier (push-queue start-node frontier))
66
        (for ([i (in-naturals)]
67
              #:break (or
68
                        (empty? frontier)
69
                        (is-goal (second current-node))))
70
          (set!-values (current-node frontier) (pop-queue frontier))
71
          (set! visited-states
72
                 (push-set
73
                  (second current-node)
74
                 visited-states))
75
          (for ([succ
76
                  (aet-succ
77
                   (second current-node))]
78
                 #:unless (ismember? (second succ) visited-states))
79
             (set! frontier
80
                   (push-queue
81
                    (list
82
                     (cons (first succ) (first current-node))
83
                     (second succ))
84
                    frontier)))
85
86
        (if (is-goal (second current-node))
87
             (reverse (first current-node))
88
            #f)))
```

A* Version

```
59
    (define (A-star maze heuristic-fun)
      (let ([start-node (list null maze)]
60
61
             [frontier (make-priority-queue
62
                        (g-func heuristic-fun))]
63
             [visited-states (make-set)]
64
             [current-node null])
65
        (set! current-node start-node)
66
        (set! frontier (push-priority-queue start-node frontier))
67
        (for ([i (in-naturals)]
68
              #:break (or
69
                        (empty? frontier)
70
                        (is-goal (second current-node))))
71
           (set!-values (current-node frontier) (pop-priority-queue frontier))
72
          (set! visited-states
73
                 (push-set
74
                  (second current-node)
75
                 visited-states))
76
          (for ([succ
77
                  (get-succ
78
                   (second current-node))]
79
                #:unless (ismember? (second succ) visited-states))
80
            (set! frontier
81
                   (push-priority-queue
82
                    (list
83
                     (cons (first succ) (first current-node))
84
                     (second succ))
85
                   frontier)))
86
87
        (if (is-goal (second current-node))
88
            (reverse (first current-node))
89
            #f)))
```

A* Version

```
59
    (define (A-star maze heuristic-fun)
      (let ([start-node (list null maze)]
60
61
             [frontier (make-priority-queue
62
                        (g-func heuristic-fun))]
63
             [visited-states (make-set)]
64
             [current-node null])
65
        (set! current-node start-node)
66
        (set! frontier (push-priority-queue start-node frontier))
67
        (for ([i (in-naturals)]
68
              #:break (or
69
                        (empty? frontier)
70
                        (is-goal (second current-node))))
71
           (set!-values (current-node frontier) (pop-priority-queue frontier))
72
          (set! visited-states
73
                 (push-set
74
                  (second current-node)
75
                 visited_states))
76
          (for ([succ
77
                  (aet-succ
78
                   (second current-node))]
79
                #:unless (ismember? (second succ) visited-states))
80
            (set! frontier
81
                   (push-priority-queue
82
                    (list
83
                     (cons (first succ) (first current-node))
84
                     (second succ))
85
                    frontier)))
86
87
        (if (is-goal (second current-node))
88
             (reverse (first current-node))
89
            #f)))
```

Note that the function used to prioritize nodes in the priority queue is not the heuristic function, but the heuristic function plus the cost function (this sum gives the f function, which is used by A*).

A note on state representations

The solution shown here uses the state representation given to the problem, which is a matrix representing the positions of everything in the maze.

Other representations can be used, but to solve the search for more than one food and avoid loops a representation must be able to tell that:

