

ASB4



Raleigh, NC • NCState
August 2-5, 2016



Quantifying Human Augmentation State-of-the-Art & Future Challenges



Human augmentation: an exciting few years

2014

2015

2016

Human augmentation: an exciting few years

ReWalk



2014

2015

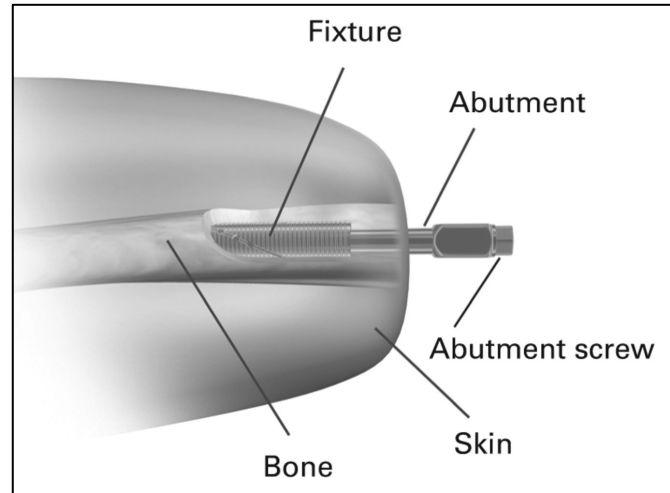
2016



DEKA

Human augmentation: an exciting few years

ReWalk



Osseointegration

2014

2015

2016



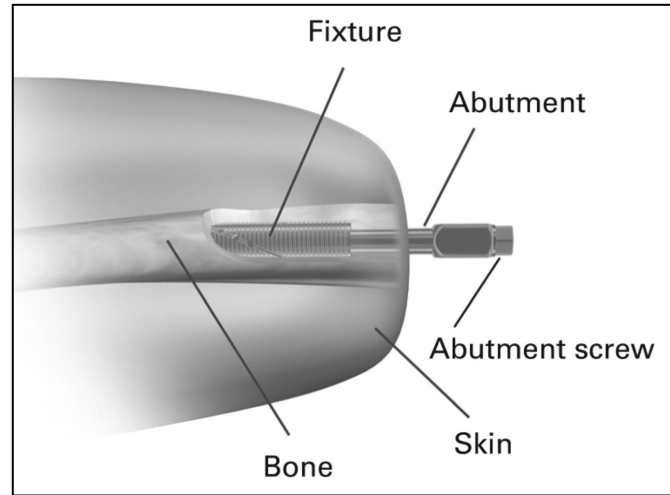
DEKA

Human augmentation: an exciting few years

ReWalk



2014



Osseointegration

2015

Parker
Indego



2016



DEKA

Ekso GT



New fabrication methods & compliant mechanisms



Exoskeletons: \$68 million worth sold in 2014



Exoskeletons: \$68 million worth sold in 2014



x 40% CAGR

(compounded annual growth rate)

Exoskeletons: \$1.8 billion projected for 2025

2014



2025



What does this mean for biomechanics community?

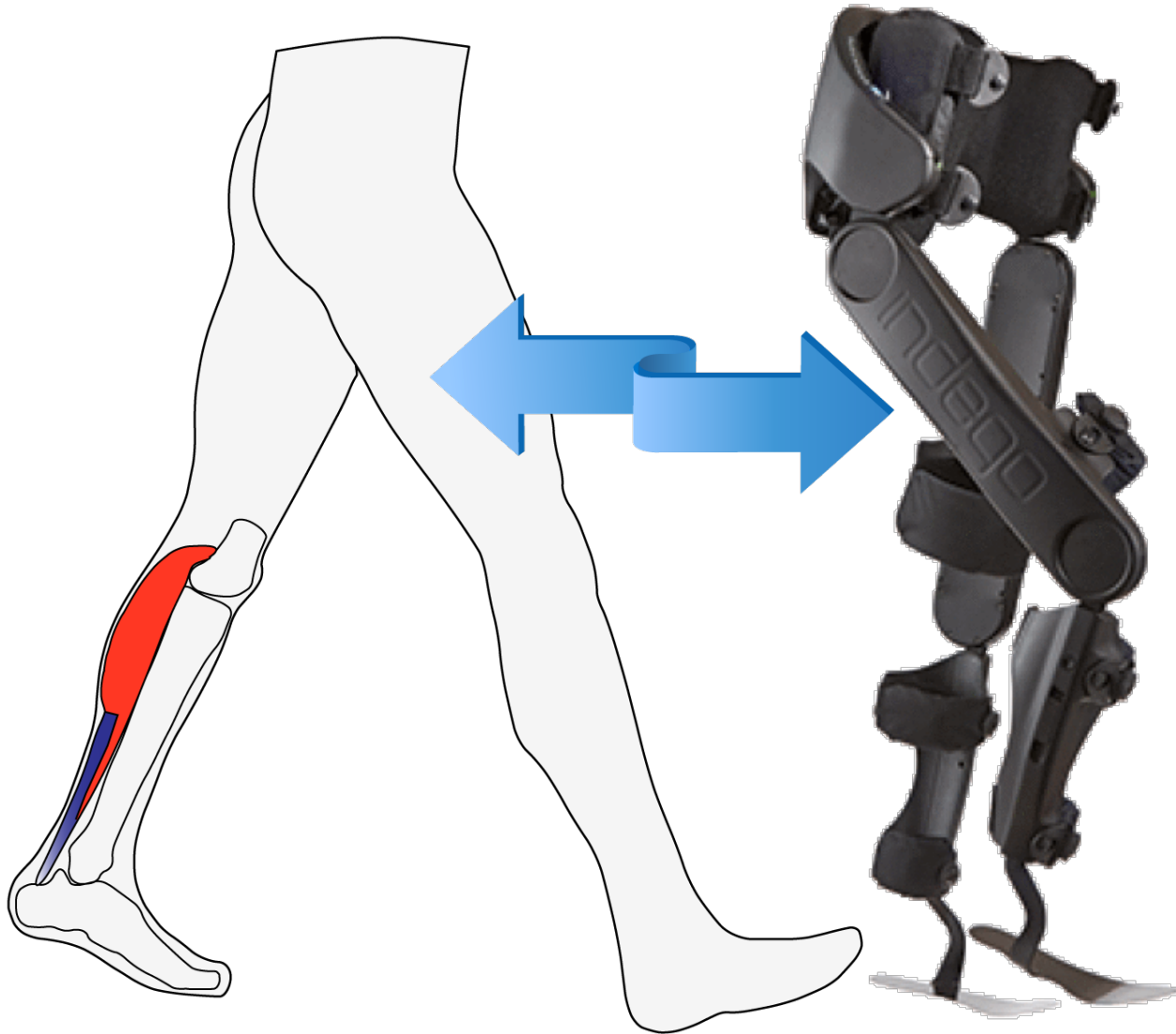
2014



2025



What does this mean for biomechanics community?



How do we quantify human augmentation?

Device Performance



Utility: verification,
system identification

Metrics: torque,
power, bandwidth

Knowledge: excellent

How do we quantify human augmentation?

Device Performance

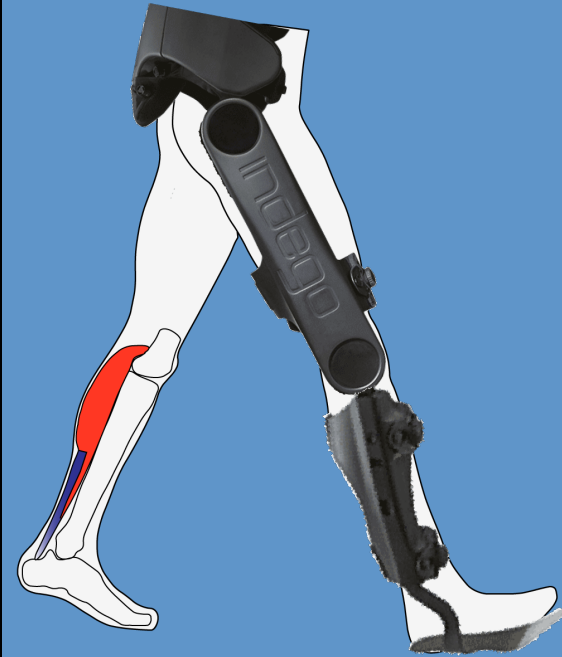


Utility: verification,
system identification

Metrics: torque,
power, bandwidth

Knowledge: excellent

Human-Device Performance



Utility: validation,
prescription, advertising

Metrics: metabolic cost,
functional outcomes

Knowledge: good

How do we quantify human augmentation?

Device Performance

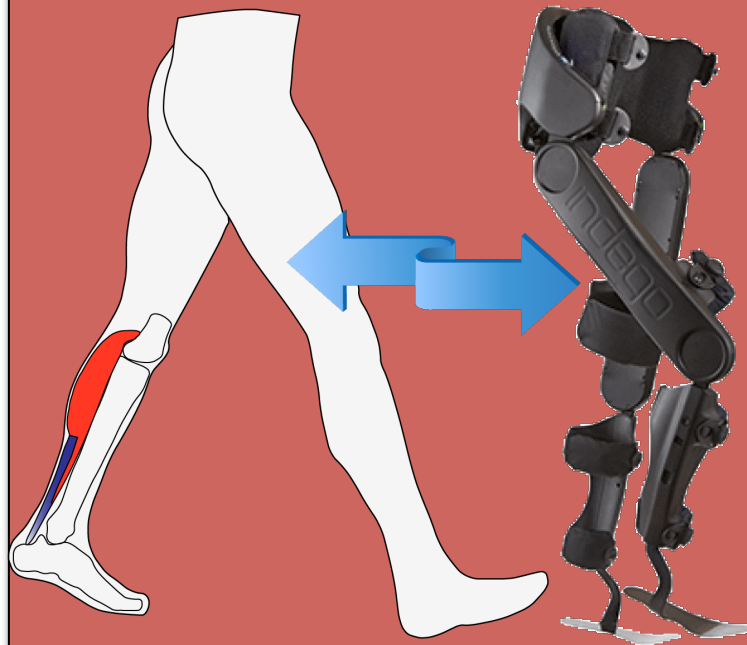


Utility: verification, system identification

Metrics: torque, power, bandwidth

Knowledge: excellent

Human-Device Interaction

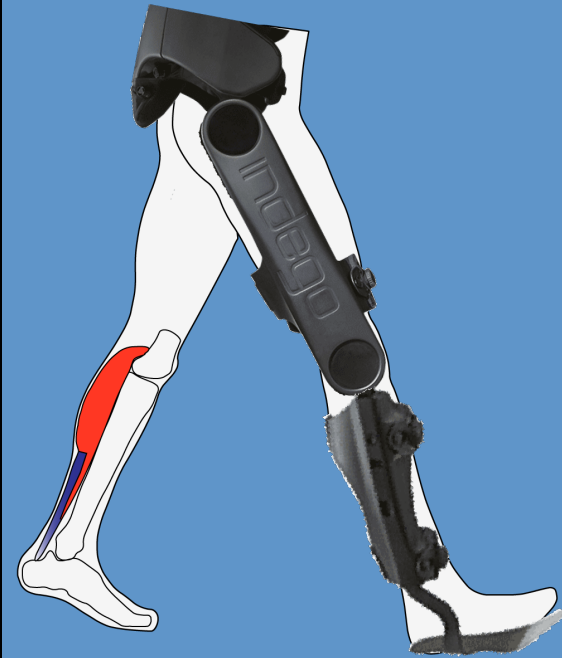


Utility: inform science, device design & control

Metrics: relative motion & power contributions, adaptation

Knowledge: lacking

Human-Device Performance



Utility: validation, prescription, advertising

Metrics: metabolic cost, functional outcomes

Knowledge: good

15 MINUTES

1. Quantifying contribution of non-biomimetic technologies



Steven Stanhope
(Delaware)

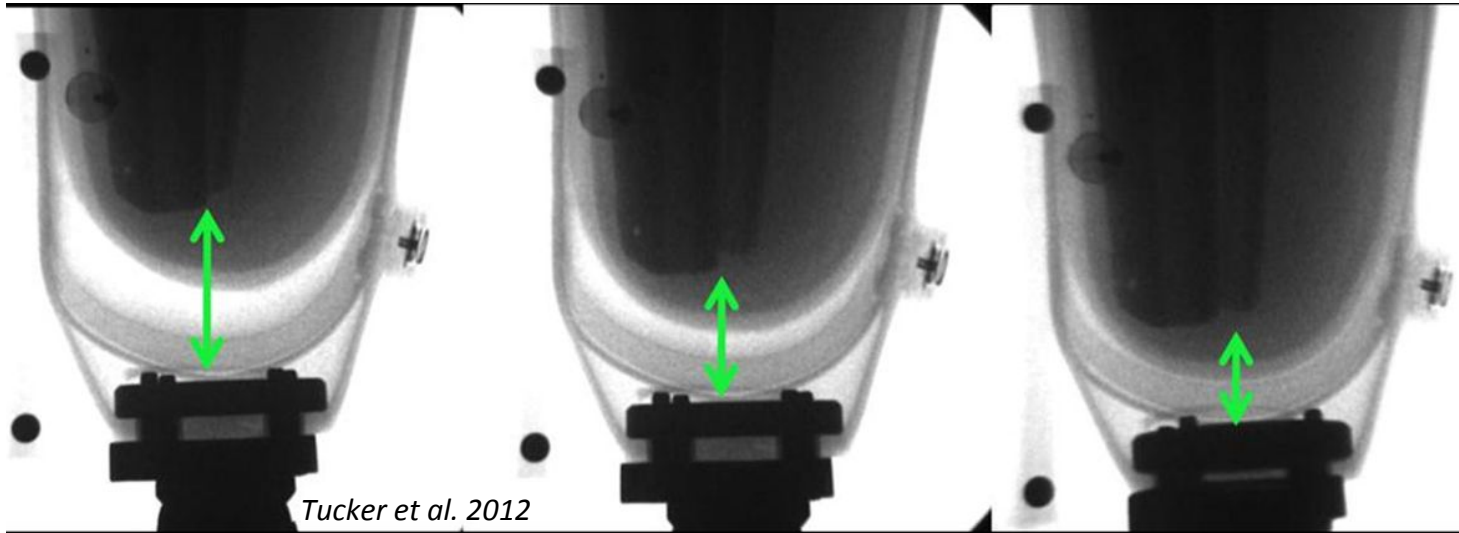
15 MINUTES

1. Quantifying contribution of non-biomimetic technologies



Steven Stanhope
(Delaware)

2. Quantifying motion between device & human and implications for motor control



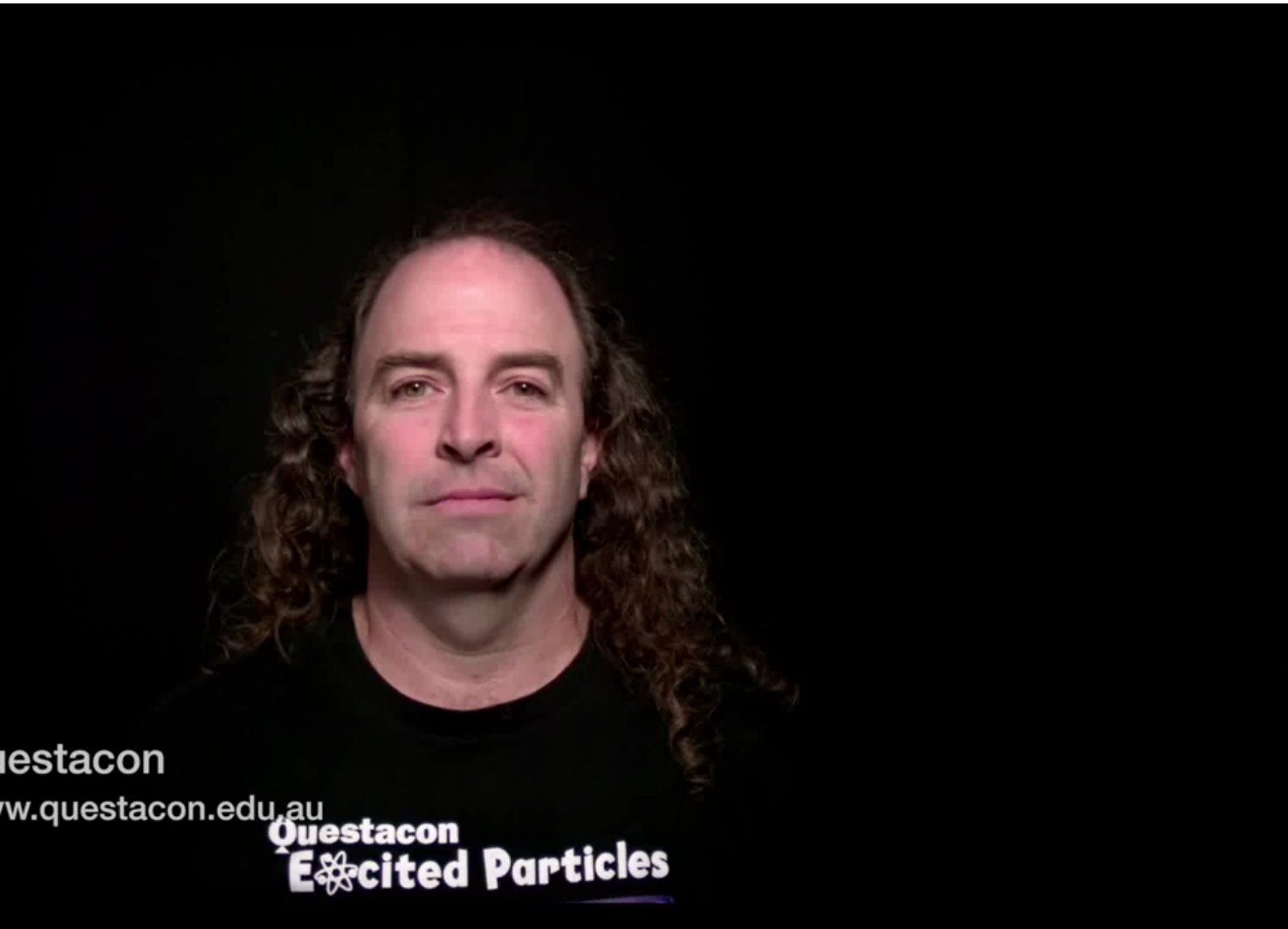
prosthetic socket pistoning



Lee Childers
(Georgia Tech)

8 MINUTES

3. Quantifying power transfer between device & human

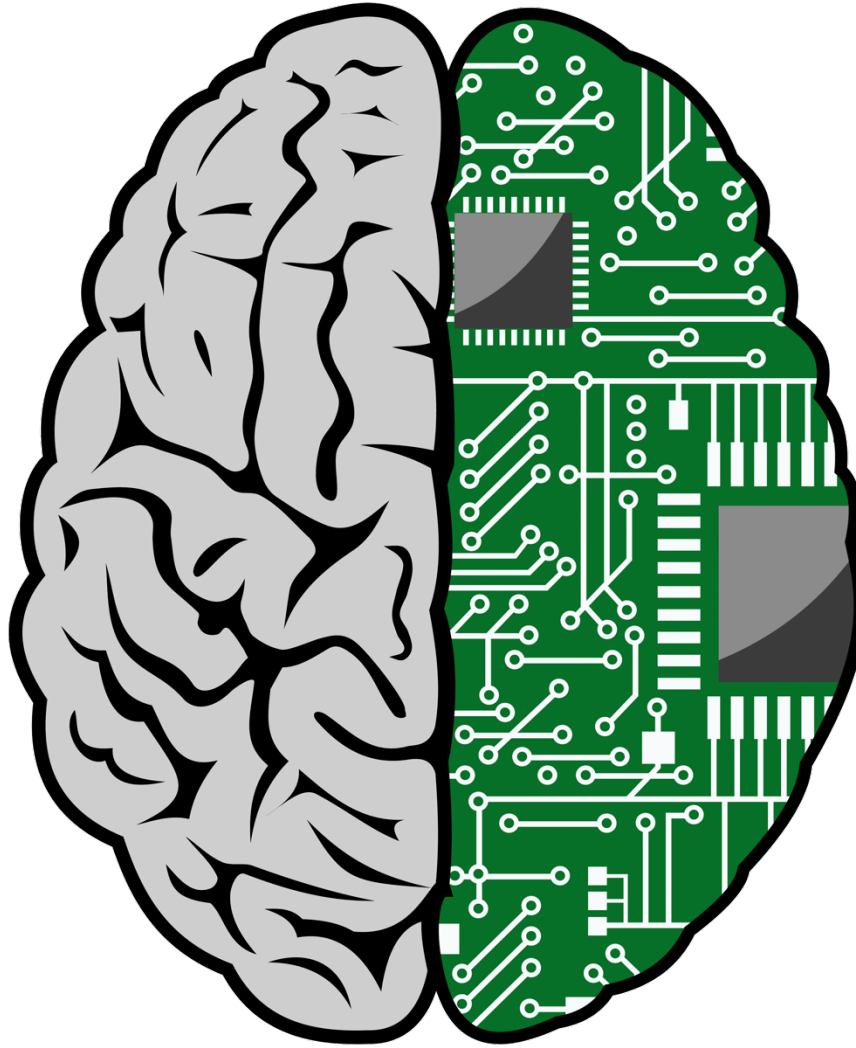


Karl Zelik
(Vanderbilt)

15 MINUTES

4. Adaptive control of devices & controller errors

and implications for quantifying performance



Helen Huang
(NC State)

5. Learning to use novel robotic devices

and implications for quantifying performance



Daniel Ferris
(Michigan)

5. Learning to use novel robotic devices

and implications for quantifying performance

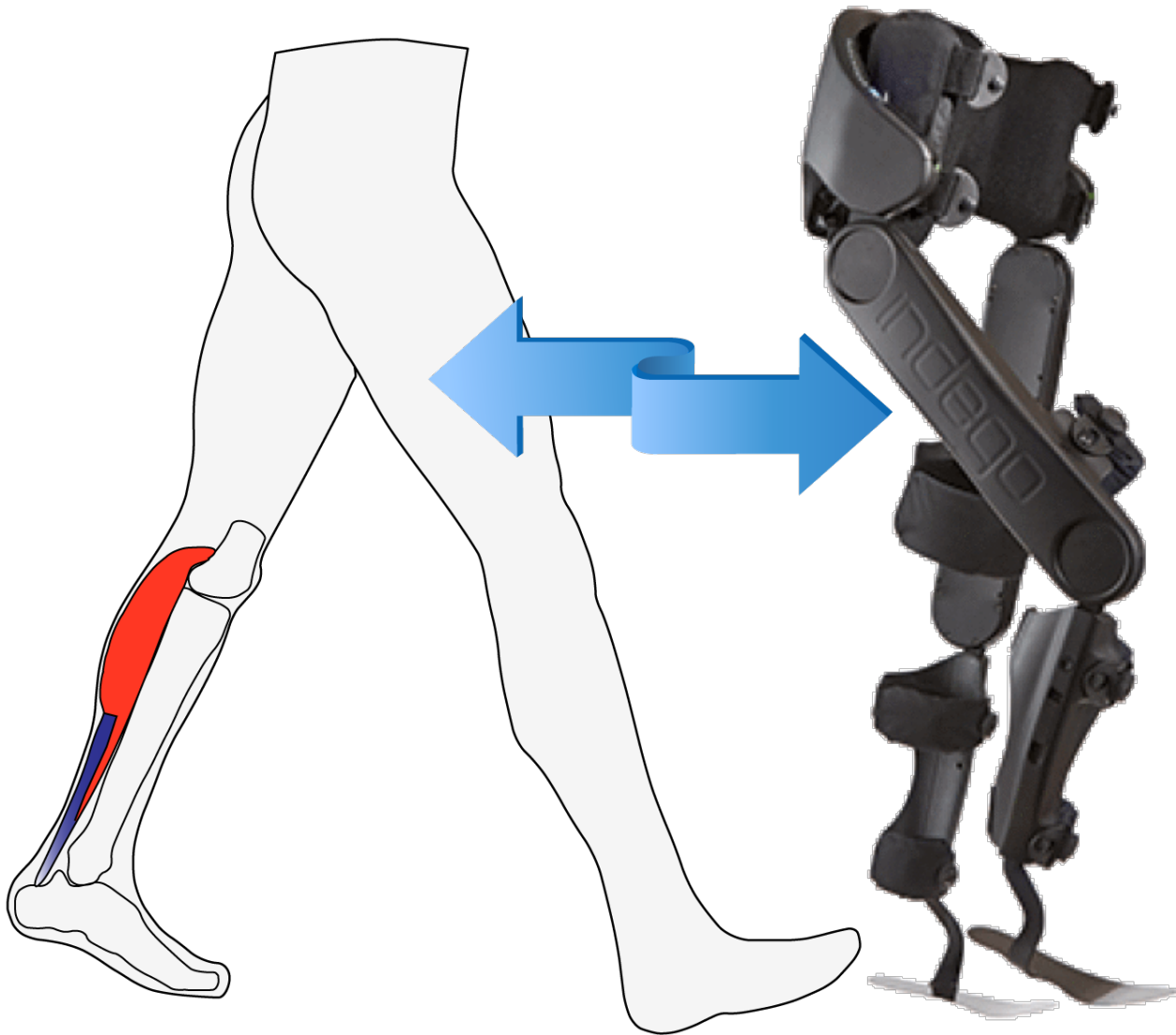


Daniel Ferris
(Michigan)

15 MINUTES

6. Group Discussion on Quantifying Human Augmentation

state-of-the-art & future challenges



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