

# Beyond the Lab: Four Use-Inspired Applications of Intelligent Systems for Societal Challenges

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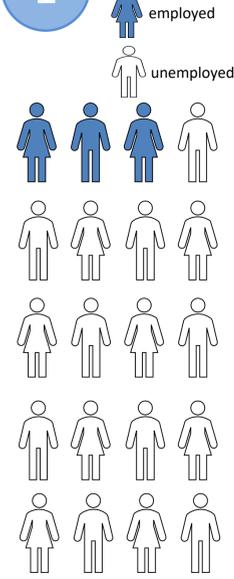
## ABSTRACT

The Robotics and Autonomous Systems Lab (RASL) focuses on the creation of intelligent systems to address societal needs. Presented here are projects that focus on addressing 3 main issues with various technologies:

- 1) **virtual reality** for soft skill training to address unemployment in autistic adults,
- 2) **wearable technologies and machine learning** for notifying caregivers of potential challenging behaviors in children with ASD,
- 3) the use of **augmented reality** to address loneliness in older adults residing in long-term care settings

*Our technological solutions in each project have been developed with stakeholders and user input for deployment in real-world settings.*

### 1 Background



Of the 5,437,988 autistic adults in the United States, **85%** are under or unemployed

In collaboration with the Frist Center for Autism and Innovation, we aim to address two of the common barriers to employment for autistic adults: the interview process and collaboration in the workplace

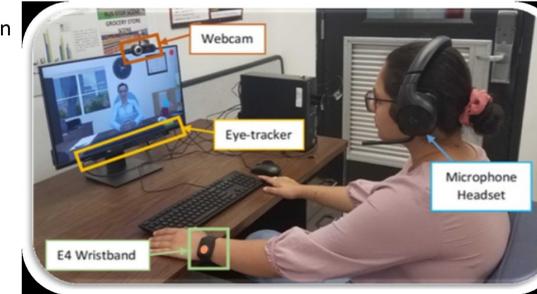


#### Project Objectives

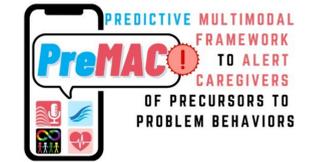
- Provide an AI-adaptive, engaging, and individualized interview experience to practice interviewing skills
- Visualization of data to provide feedback to autistic individuals
- Data analysis to provide recommendations to employers on how to improve the interview process for autistic individuals

#### Project Components

- Conversation Module With Bidirectional Communication
- Emotion Detection Module Via Facial Expressions
- Eye Gaze Detection Module
- Physiology-based Stress Detection Module



### 2 Background



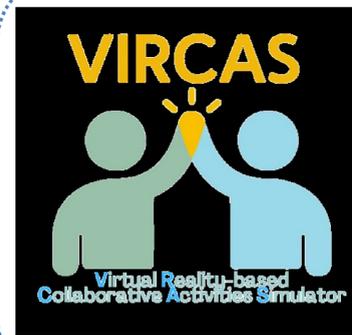
Approximately **50%** of children and adolescents with Intellectual and Development Disorders (IDD) exhibit challenging behaviors (self injurious behaviors, aggression toward others, elopement, etc.)

#### Project Objectives

- Develop an unobtrusive and well-tolerated wearable sensor network for sensing multimodal inputs (e.g., physiology, limb movement, vocal tone etc.) and create a real-time machine learning model grounded in state-of-the-art clinical intervention for predicting precursors to challenging behaviors in children and young adults with IDD
- Apply, test, and validate the new precursor detection framework in real-world intervention studies in several clinics in and around Nashville

#### Project Components

- Customized Hardware To Capture Motion, Electrodermal Activity, and Heart Rate
- Audio Is Collected and Mel Frequency Is Extracted
- Multimodal Data Is Used To Train A Realtime Predictive Model

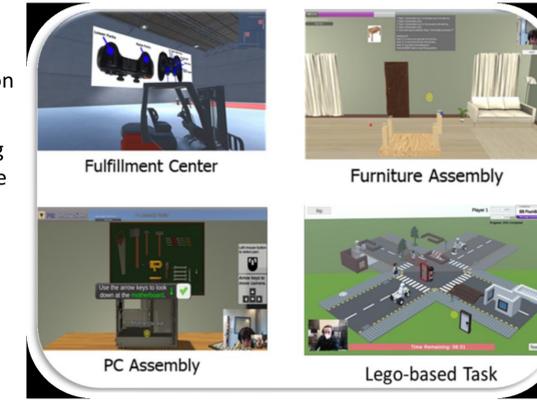


#### Project Objectives

- Create an interactive, engaging, and easy-to-access virtual-reality based simulator that can support teamwork skills training
- Provide a quantitative measurement and evaluation of teamwork skills through the analysis of multimodal data

#### Project Components

- A Wide Range Of Collaboration Features
- A Video And Audio Streaming Service Embedded Within The Virtual Environment
- A Multimodal Data Capture Module
- A Network Communication Layer In The Virtual Environment



### 3 Background



#### Background

**75%** of older adults living in long-term care facilities report experiencing loneliness. Loneliness has been linked to increases in heart disease, depression, and reduced quality of life.

#### Project Objectives

- Develop a novel Collaborative Augmented Reality (CAR) framework to increase *social presence* in interactive communication technology where photorealistic 3-D avatars of an older adult's family members will be transported to their room in LTC for real-time joint activities with appropriate verbal and nonverbal communication
- Apply the above developed framework to develop CAR activities to mitigate loneliness among older adults in long-term care (LTC) settings, study its implementation, challenges, and impact

#### Project Components

- Bidirectional Networking Between Multiple AR Head Mounted Displays
- Facial And Body Gesture Mapping Between Local User and Their Remote Avatar
- Dynamically Weighted Body Pose Optimization During Avatar-object Interaction
- Spatiotemporal Rectified Mapping Of Locomotion Between User and Avatar Environments

## Acknowledgements

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